



## Manipulator Servo Level World Modeling (Classic Reprint) (Paperback)

By Laura Kelmar

Forgotten Books, 2017. Paperback. Condition: New. Language: English . Brand New Book \*\*\*\*\* Print on Demand \*\*\*\*\*.Excerpt from Manipulator Servo Level World Modeling A manipulator control system, such as the one described in [alb87], allows for many controlled devices, as well as many sensors. For example, the Task Decomposition hierarchy may provide servo control for the camera lens, the gripper, and the manipulator joints, while the Sensory Processing hierarchy may process camera images, tactile arrays, and manipulator joint data. In general, each device requires separate World Modeling support at each level. That is, a complete pictorial representation of the control hierarchy would contain a separate World Modeling box for each device and associated sensor. The scope of this document is limited to the discussion of the World Model module at the Servo Level of a manipulator control system, as highlighted in figure 3. We briefly discuss the function of the Level 1 Sensory Processing module in supplying manipulator sensor readings. About the Publisher Forgotten Books publishes hundreds of thousands of rare and classic books. Find more at This book is a reproduction of an important historical work. Forgotten Books uses state-of-the-art technology to digitally reconstruct the work, preserving the original...



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