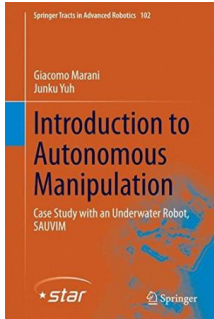


Download Doc

## INTRODUCTION TO AUTONOMOUS MANIPULATION CASE STUDY WITH AN UNDERWATER ROBOT, SAUVIM SPRINGER TRACTS IN ADVANCED ROBOTICS



Springer. Hardcover. Condition: New. 162 pages. Dimensions: 9.2in x 6.2in x 0.7in. Autonomous manipulation is a challenge in robotic technologies. It refers to the capability of a mobile robot system with one or more manipulators that performs intervention tasks requiring physical contacts in unstructured environments and without continuous human supervision. Achieving autonomous manipulation capability is a quantum leap in robotic technologies as it is currently beyond the state of the art in robotics. This book addresses issues with the complexity of..

**Read PDF Introduction to Autonomous Manipulation Case Study with an Underwater Robot, SAUVIM Springer Tracts in Advanced Robotics**

- Authored by Junku Yuh
- Released at -



Filesize: 7.18 MB

### Reviews

*Most of these pdf is the best pdf offered. It can be rally fascinating throug studying period of time. You may like just how the writer write this pdf.*

-- **Carlie Bahringer IV**

*This written publication is wonderful. It can be writter in straightforward phrases instead of confusing. I discovered this pdf from my dad and i suggested this publication to learn.*

-- **Jesse Tremblay**

*This pdf is very gripping and fascinating. We have read and that i am certain that i am going to going to read once more again in the future. Once you begin to read the book, it is extremely difficult to leave it before concluding.*

-- **Burnice Cronin**